

EE 597

July 13, 2016

About the midterm exam:

Q2 & Q3

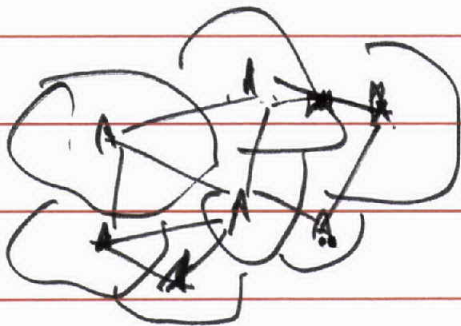
- involved modeling of the problem
 - identifying relevant expressions or conditions
 - formulating the optimization problem
 - stochastic channels.

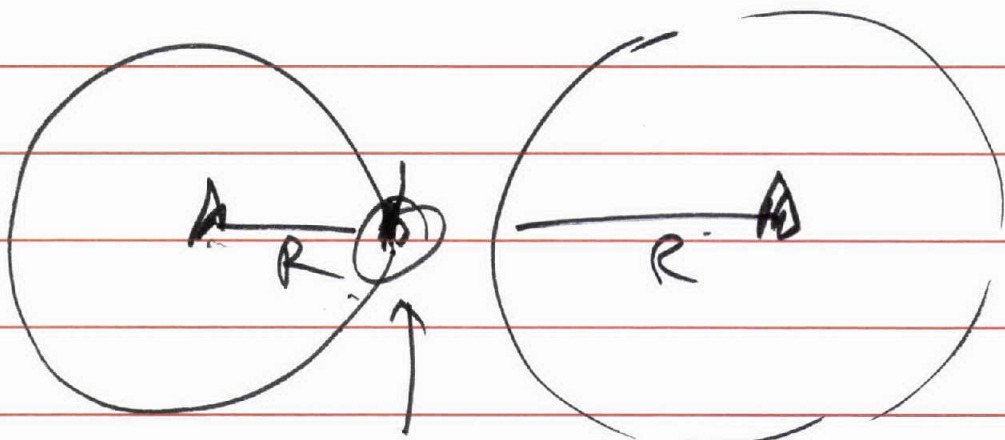
needs the 503 prereq.

Why do we bring in Probability into Wireless Networks?

How much do we really need?

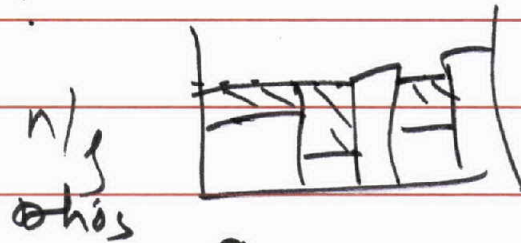
E.g.: (log normal fading) ← channel quality is random





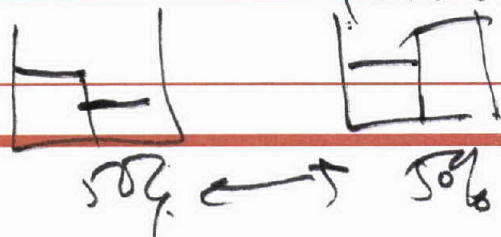
cell-edge user experiencing the lowest SINR

Waterfilling:



only suitable for slow fading channels.

for fast fading, the (P/n) ratios will be (stochastically varying)



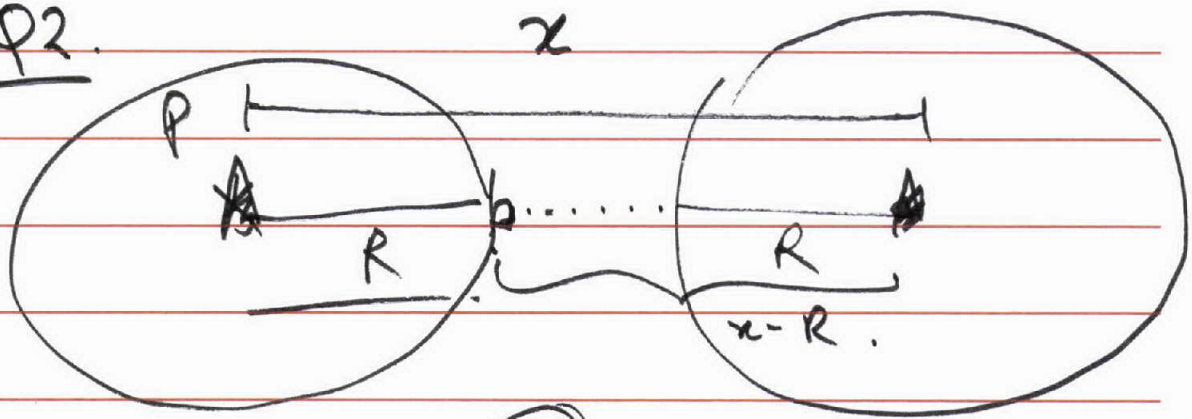
Time constant of change determines whether we can solve the problem as a classical/deterministic optimization problem or as a stochastic/probabilistic optimization problem.

typically: given some variable that has

i.e. it is unknown/has uncertainty.

a distribution, & the performance objective depends on it. Goal: MAX the Expected Performance.

Q2.



a) $SINR = \frac{S}{I + N}$ $x - R$

$P \cdot \left(\frac{R}{d_0}\right)^{-\eta} \cdot K \cdot \psi_1$ log normal r.v.

$P \cdot \left(\frac{x - R}{d_0}\right)^{-\eta} \cdot K \cdot \psi_2 + N$ $> T$

both log normal r.v.

b) Rewrite in the dB scale: $\sim N(0, \sigma^2)$

$SINR_{dB} = P_{dBm} - \eta 10 \log_{10} \left(\frac{R}{d_0}\right) + \psi_1_{dB}$

$- \left(P_{dBm} - \eta 10 \log_{10} \left(\frac{x - R}{d_0}\right) + \psi_2_{dB} \right)$

$$Y \sim N(0, 2\sigma^2)$$

for outage

$$\frac{\gamma_{1dB} - \gamma_{2dB}}{\text{Normal r.v.}}$$

$$- \eta_{10} \log_{10}(R) + \eta_{10} \log_{10}(R-x)$$

$$< T_{dB}$$

Normal r.v.

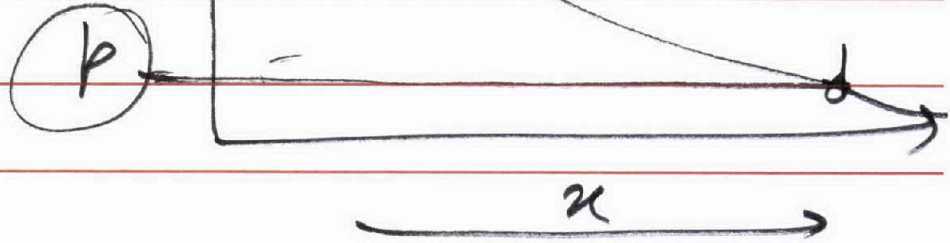
$$Y < T_{dB}$$

$$T_{dB} - \eta_{10} \log_{10}(R) + \eta_{10} \log_{10}(R-x)$$

for outage

$$P_{out} = P(Y < T_{dB} - \eta_{10} \log_{10}(R) + \eta_{10} \log_{10}(R-x))$$

$P_r(\text{outage})$



Q3. max the expected sum rate:

$$\log\left(1 + P_1 \frac{g_1}{n_1}\right) +$$
$$0.5 \log\left(1 + P_2 \frac{g_2}{n_2}\right)$$
$$0.5 \log\left(1 + P_2 \frac{G_2}{N_2}\right)$$

? $\log\left(1 + 0.5 P_2 \frac{g_2}{n_2} + 0.5 P_2 \frac{G_2}{N_2}\right)$

Expected rate for ch 2. Expected SNR.

$$E[f(X)] \neq f(E[X])$$

$$\text{Expected}(\log(1 + \text{SNR})) \neq \log(1 + E[\text{SNR}])$$

Can also formulate as:

$$f(x) = \log\left(1 + x \frac{h_1}{n_1}\right) +$$

$$\frac{1}{2} \left(\log\left(1 + (P_{\text{tot}} - x) \frac{h_2}{n_2}\right) +$$

$$\log\left(1 + (P_{\text{tot}} - x) \frac{G_2}{n_2}\right) \right)$$

$$0 \leq x \leq P_{\text{tot}}$$

$$\frac{df(x)}{dx} = 0$$

more general case: arbitrary pmf
for each channel.

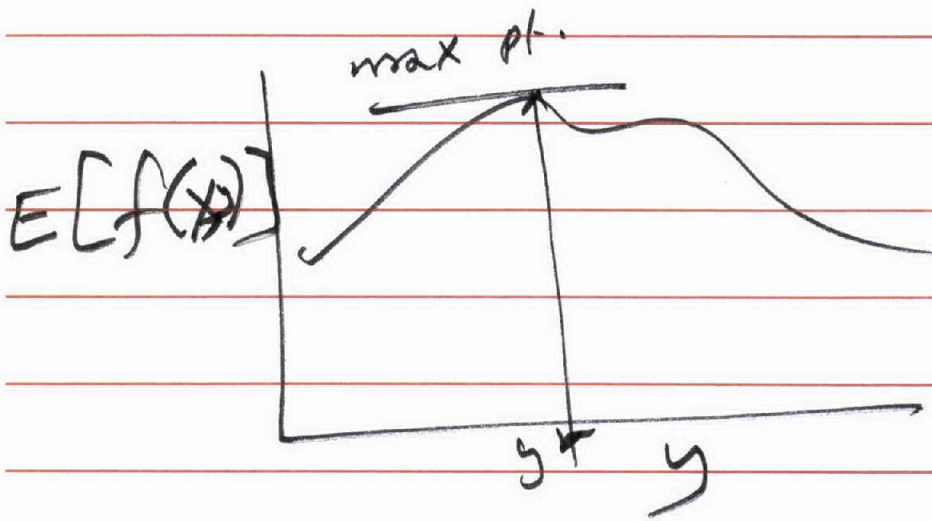
$$\text{Rate 1} = E[\log(1 + \text{SNR}_1)]$$

$$\text{Rate 2} = E[\log(1 + \text{SNR}_2)]$$

$$E[f(x)] = \sum_{x_k} p_X(x_k) \cdot f(x_k)$$

x_k

$$\log\left(1 + P_i \frac{h_i}{n_i}\right)$$



r.v.

say the r.v. / parameter(s) with ↓
uncertainty in the problem is \underline{X}
(random vector)

The design variable(s), which we
can control (to improve performance)

is \underline{y}

deterministic,
not random

Performance metric $f(\underline{X}, \underline{y})$

depends on uncertain env.
& The design variable

In the waterfilling probm:

$f(x, y)$ metric: sum of expected rates.

$$E[\log(1 + \text{SNR}_1)] + E[\log(1 + \text{SNR}_2)]$$

$$\text{SNR}_1 = P_1 \frac{g_1}{n_1} \quad \text{SNR}_2 = P_2 \frac{g_2}{n_2}$$

$$E_{\underline{X}} [f(\underline{X}, y)] \leftarrow f(y)$$

is expectation wrt to the (jt.) distribution of \underline{X}

Goal:

$$\max_y f(y)$$

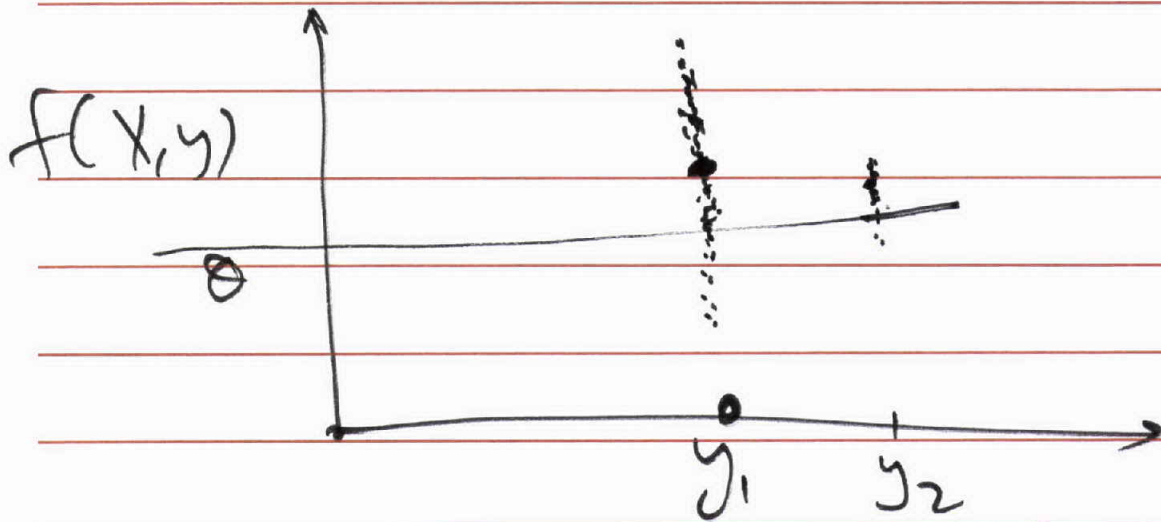
It is a deterministic function of y alone, has no dep. on \underline{X} anymore.

Given uncertain environment \underline{X} ,
design \underline{y} , performance
metric $f(\underline{X}, \underline{y})$

1. $\max E[f(\underline{X}, \underline{y})]$

2. ensure that $\Pr[f(\underline{X}, \underline{y}) < \theta]$
is as low as possible.
also $\theta \approx f(\underline{y})$

Performance for a fixed \underline{y} .



$$E[f(X, y_1)] > E[f(X, y_2)]$$

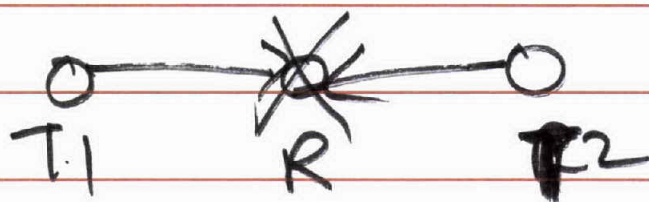
but $\Pr[f(X, y_2) < \theta] \neq$

$$\Pr[f(X, y_1) < \theta]$$

Wrap up on LINK/MAC layer

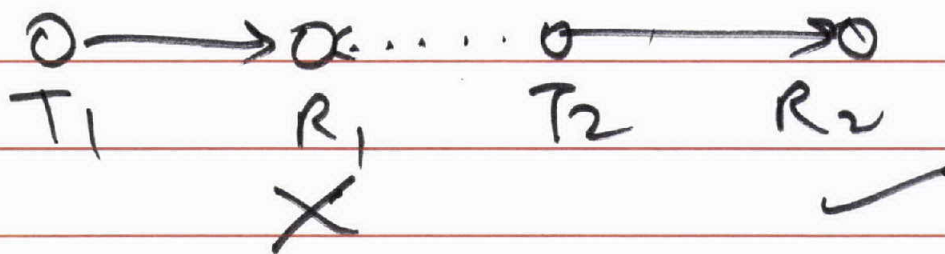
RTS-CTS mechanism for CSMA

Hidden Node/Terminal Problem.



Unexpected

Collision



problem occurs because
sensing is at the sender

sender
sends

RTS - request to send

recv:
sends

CTS - clear to send,

if channel is free at
the receiver.

Reduces collisions but has higher overhead

New class of MAC protocols have been developed in the last 10-15 years for "Low-Power Wireless Embedded Devices" that are a significant part of the future IoT systems.

Internet of Things

often involve Energy-constrained devices running on batteries, that for long lifetimes must spend a lot of time asleep.



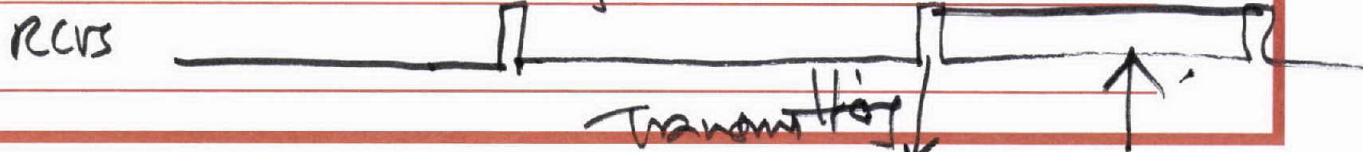
option 1: schedule the sleep (Synchronous sleep) periods & only communicate during known active times.

- low power devices are typically using cheap HW - get desynchronized
- mobilities

Option 2 Asynchronous sleep.

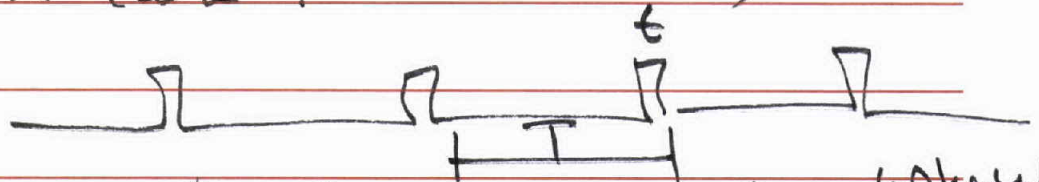
1. Transmitter - Initiated schemes
2. Receiver - Initiated schemes.

1. Also called
Low Power Listening
wakeup



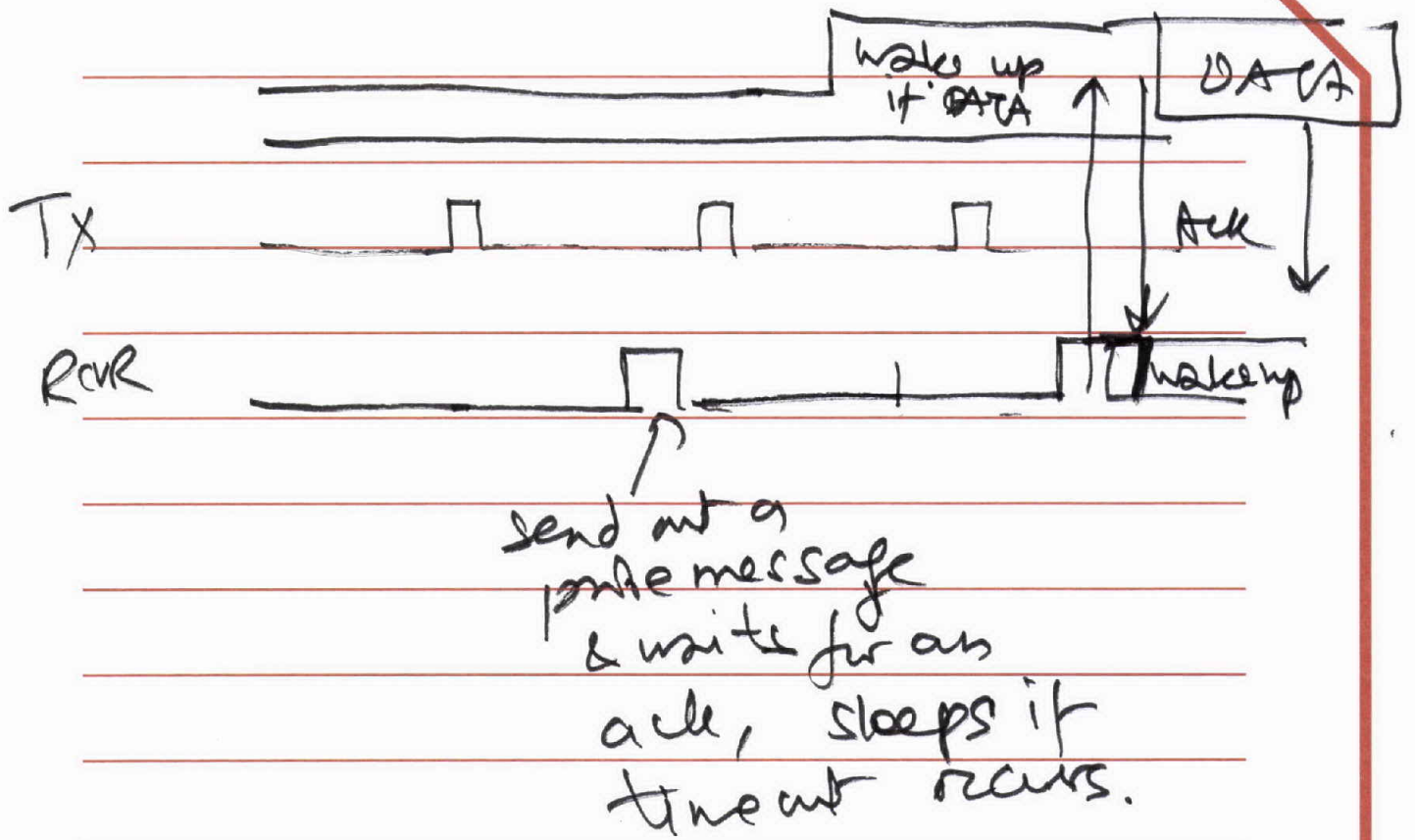
how long?
Long preamble

Common case: (no data)



$$\frac{t}{T} = \text{duty cycle} = \frac{\text{wakeup}}{\text{total period}}$$

preamble length $>$ total period length



Many Asynchronous Duty Cycled Sleep based MAC protocols (LPL, XMAC, AMAC) exist for Low Power Wireless/IoT devices.